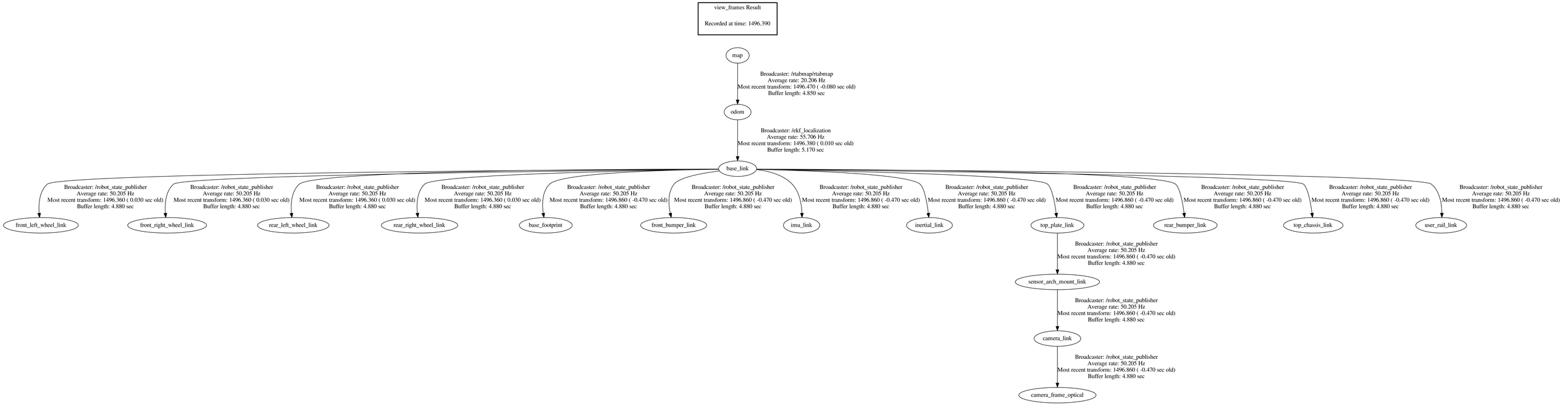
view_frames Result
Recorded at time: 1496.390
map
Broadcaster: /rtabmap/rtabmap
Average rate: 20.206 Hz
Most recent transform: 1496.470 (-0.080 sec old)
Buffer length: 4.850 sec
odom
Broadcaster: /ekf_localization
Average rate: 55.706 Hz
Most recent transform: 1496.380 (0.010 sec old)
Buffer length: 5.170 sec
base_link
Broadcaster: /robot_state_publisher
Average rate: 50.205 Hz
Most recent transform: 1496.360 (0.030 sec old)
Buffer length: 4.880 sec
front_left_wheel_link
front_right_wheel_link
rear_left_wheel_link
rear_right_wheel_link
base_footprint
Broadcaster: /robot_state_publisher
Average rate: 50.205 Hz
Most recent transform: 1496.860 (-0.470 sec old)
Buffer length: 4.880 sec
front_bumper_link
imu_link
inertial_link
top_plate_link
rear_bumper_link
top_chassis_link
user_rail_link
sensor_arch_mount_link
camera_link
camera_frame_optical